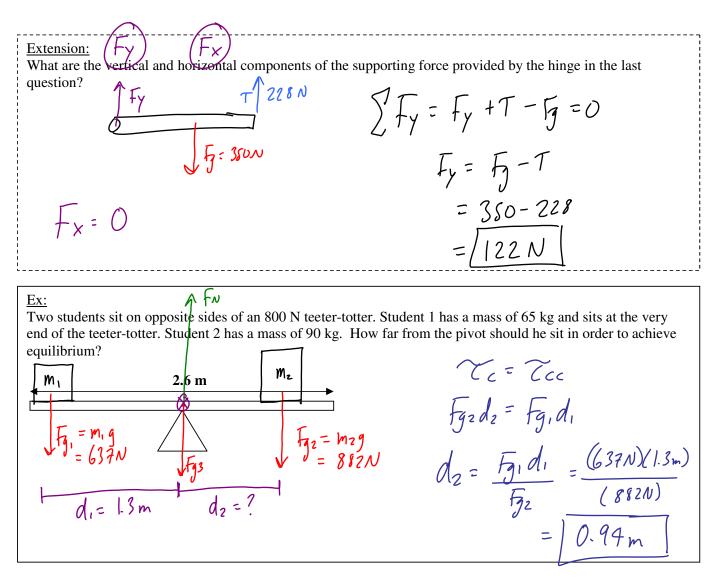
Equilibrium Notes $2 - Torque at 90^{\circ}$ A body in translational equilibrium will have no acceleration in the x or y directions. However it still could be (0141m Consider a teeter-totter, with a 100 kg student on one end and a 50 kg student on the other. What are the net translational forces in: The x-direction? $\frac{2}{5}F_{x} = 0$ The y-direction? $\frac{5}{5}F_{y} = 0$ torg Although the net translational forces are zero, the system has a \underline{Ne} it is not in equilibrium. An object in equilibrium must have both translational and volationa equilibrium. Imagine trying to loosen the lug nuts to remove a tire from The second condition of equilibrium is that in your car. The longer the wrench you use, the easier it will be. order to have no rotation, there must be no net Ex: torque. A torque of 24.0 Nm is needed to tighten a nut. If a person can apply a force of 100 N, what is the minimum length of Torque is defined as: force x distance to pivot wrench that is required? $7 = Fd \quad d = \frac{7}{F} = \frac{24.0N \cdot m}{100N} = 0.24 m$ Unit of torque: $N \cdot m$ A few more terms we need to learn before we go on... Centre of Gravity: Where the average mass acts. Where we draw Fg! Torque is a Vector quantity. which must work in either the clockwise (c) or counterclockwise (cc) directions. Uniform Beam: Constant shape and density If an object is in rotational equilibrium then: $\sum \gamma = 0$ or $\gamma_c = \gamma_{cc}$ **Arbitrary Position of Rotation:** You choose the location of privot! $d_2 = 2.0 \text{ m}$ Ex: A 350 N store sign hangs from a pole of negligible mass. The pole is attached to a wall by a hinge and supported by a vertical rope. What is the tension in the rope? $F_{gd_{1}} = Td_{2}$ $T = \frac{F_{gd_{1}}}{d_{2}} = \frac{350(1.3)}{2.0} = \frac{227.5N}{228N}$ Ø,[≠]1.3 m Fa = 3.501 Jen + Eric Store



Ex:

A 3500 kg truck is parked on a bridge as shown. If the bridge deck itself has a mass of 6500 kg find the supporting force provided by each of the two support posts.

1 2	11	T
$\mathcal{L}_{c} = \mathcal{L}_{cc}$		
$F_{N_1}d_3 = F_{\overline{2}_1}d_1 + F_{\overline{2}_2}$	dz	
$F_{N_1} = \frac{F_3 d_1 + F_3 d_2}{d_3}$		
= (34300)(5) + (637	00)(7	.5)
15		
= 43300N		

ts.

$$F_{N_1}$$

 f_{N_2}
 f_{T_2}
 f_{T_2}
 f_{T_3}
 f_{T_2}
 f_{T_3}
 f_{T_2}
 f_{T_3}
 f_{T

1

= 34300+63700-43300N = 54700N