ADVANCED PLACEMENT PHYSICS 1 TABLE OF INFORMATION

CONSTANTS AND CONVERSION FACTORS	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Electron charge magnitude, $e = 1.60 \times 10^{-19}$ C
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant, $k = 1/4\pi\varepsilon_0 = 9.0 \times 10^9\ \text{N}\cdot\text{m}^2/\text{C}^2$
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Universal gravitational constant, $G = 6.67 \times 10^{-11}\ \text{m}^3/\text{kg}\cdot\text{s}^2$
Speed of light, $c = 3.00 \times 10^8$ m/s	Acceleration due to gravity at Earth's surface, $g = 9.8\ \text{m/s}^2$

UNIT SYMBOLS								
	meter,	m	kelvin,	K	watt,	W	degree Celsius,	°C
	kilogram,	kg	hertz,	Hz	coulomb,	C		
	second,	s	newton,	N	volt,	V		
	ampere,	A	joule,	J	ohm,	Ω		

PREFIXES

Factor	Prefix	Symbol
10^{12}	tera	T
10^{9}	giga	G
10^{6}	mega	M
10^{3}	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES

θ	0°	30°	37°	45°	53°	60°	90°
$\sin\theta$	0	$1/2$	$3/5$	$\sqrt{2}/2$	$4/5$	$\sqrt{3}/2$	1
$\cos\theta$	1	$\sqrt{3}/2$	$4/5$	$\sqrt{2}/2$	$3/5$	$1/2$	0
$\tan\theta$	0	$\sqrt{3}/3$	$3/4$	1	$4/3$	$\sqrt{3}$	∞

The following conventions are used in this exam.

I. The frame of reference of any problem is assumed to be inertial unless otherwise stated.
II. Assume air resistance is negligible unless otherwise stated.
III. In all situations, positive work is defined as work done <u>on</u> a system.
IV. The direction of current is conventional current: the direction in which positive charge would drift.
V. Assume all batteries and meters are ideal unless otherwise stated.

ADVANCED PLACEMENT PHYSICS 1 EQUATIONS

MECHANICS

$v_x = v_{x0} + a_x t$

$x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$

$v_x^2 = v_{x0}^2 + 2a_x (x - x_0)$

$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$

$|\vec{F}_f| \le \mu |\vec{F}_n|$

$a_c = \frac{v^2}{r}$

$\vec{p} = m\vec{v}$

$\Delta \vec{p} = \vec{F}\,\Delta t$

$K = \frac{1}{2} m v^2$

$\Delta E = W = F_{\parallel} d = Fd\cos\theta$

$P = \frac{\Delta E}{\Delta t}$

$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$

$\omega = \omega_0 + \alpha t$

$x = A\cos(2\pi f t)$

$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$

$\tau = r_{\perp} F = rF\sin\theta$

$L = I\omega$

$\Delta L = \tau\,\Delta t$

$K = \frac{1}{2} I \omega^2$

$|\vec{F}_s| = k|\vec{x}|$

$U_s = \frac{1}{2} k x^2$

$\rho = \frac{m}{V}$

$\Delta U_g = mg\,\Delta y$

$T = \frac{2\pi}{\omega} = \frac{1}{f}$

$T_s = 2\pi\sqrt{\frac{m}{k}}$

$T_p = 2\pi\sqrt{\frac{\ell}{g}}$

$|\vec{F}_g| = G\frac{m_1 m_2}{r^2}$

$\vec{g} = \frac{\vec{F}_g}{m}$

$U_G = -\frac{G m_1 m_2}{r}$

a = acceleration
d = distance
E = energy
f = frequency
F = force
h = height
I = rotational inertia
K = kinetic energy
k = spring constant
L = angular momentum
ℓ = length
m = mass
P = power
p = momentum
r = radius or separation
T = period
t = time
U = potential energy
V = volume
v = speed
W = work done on a system
x = position
α = angular acceleration
μ = coefficient of friction
θ = angle
ρ = density
τ = torque
ω = angular speed

ELECTRICITY

$|\vec{F}_E| = k\frac{|q_1 q_2|}{r^2}$

$I = \frac{\Delta q}{\Delta t}$

$R = \frac{\rho \ell}{A}$

$I = \frac{\Delta V}{R}$

$P = I\,\Delta V$

$R_s = \sum_i R_i$

$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$

A = area
F = force
I = current
ℓ = length
P = power
q = charge
R = resistance
r = separation
t = time
V = electric potential
ρ = resistivity

WAVES

$\lambda = \frac{v}{f}$

f = frequency
v = speed
λ = wavelength

GEOMETRY AND TRIGONOMETRY

Rectangle
$A = bh$

Triangle
$A = \frac{1}{2} bh$

Circle
$A = \pi r^2$
$C = 2\pi r$

Rectangular solid
$V = \ell w h$

Cylinder
$V = \pi r^2 \ell$
$S = 2\pi r \ell + 2\pi r^2$

Sphere
$V = \frac{4}{3}\pi r^3$
$S = 4\pi r^2$

A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius

Right triangle
$c^2 = a^2 + b^2$
$\sin\theta = \frac{a}{c}$
$\cos\theta = \frac{b}{c}$
$\tan\theta = \frac{a}{b}$